NEEV PARIKH

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Jul 2022 – Present

San Francisco, CA

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EXPERIENCE

Software Engineer II

Stripe

- Building a ML-based sales and marketing platform.
- Built polished data-repair tooling for self-serve, developer use, which drove self-serve repairs from 60% to 90%, increased system adoption from 40% to 60%, and saved 120 hours per year.
- Built high-performance, **5min** time-to-alert, automated testing system in Java, with instrumented metrics like availability and latency.
- Built terabyte-per-hour scale, Hadoop-based data pipelines in Scala Spark to ingest financial data in a double-entry, event-based, immutable log.

Research Engineering Intern

Common Sense Machines

- **i** May 2021 Aug 2021 Boston, MA
- · Implemented large-scale, auto-regressive Seq2Seq models for working with 3D geometry from images.
- Worked with Deepspeed to explore scaling options for **500M+** param models to feasibly scale existing sequence-based models.
- · Implemented a Blender-based Gym environment for RL to optimize textures on a 3D model.
- Implemented a graphics algorithm to find surface patches in a 3D wireframe (Zhang et. al., 2013)
- Dockerized AWS pipeline to create cloud-independent dev/production environment.

Research Assistant

Brown University

· Worked on original research on unsupervised, representation learning and multi-task reinforcement learning; see publications.

Machine Learning Intern

Myelin Foundry

- Developed a cutting-edge, deep-learning based pipeline in Pytorch and Tensorflow to augment VFX workflows for a POC product.
- Researched and managed a company-wide, cloud-compute platform, reducing potential monthly costs by **70%**.
- Implemented DeepLabv3+ from ECCV 2018 to develop SOTA pipelines for semantic segmentation tasks.
- Achieved **90%** in business-aligned metrics with reasonable inference time.

PUBLICATIONS

- N. Parikh^{*}, Z. Horvitz^{*}, N. Srinvasan^{*}, A. Shah, and G. Konidaris (Oct. 2020). "Graph Embedding Priors for Multi-task Deep Reinforcement Learning". In: NeurIPS 2020. KR2ML Workshop.
- C. Allen, N. Parikh, and G. Konidaris (Dec. 2021). "Learning Markov State Abstractions for Deep Reinforcement Learning". In: 34th Neural Information Processing Systems Conference 2021.
- K. Asadi, N. Parikh, R. Parr, G. Konidaris, and M. Littman (Sept. 2020). "Deep Radial-Basis Value Functions for Continuous Control". In: 35th AAAI Conference on Artificial Intelligence 2021.
- M. Merlin, N. Parikh, E. Rosen, and G. Konidaris (May 2020). "Locally Observable Markov Decision Process". In: International Conference on Robotics and Automation. Workshop on Perception, Action, Learning.

EDUCATION

M.Sc. in Computer Science **Brown University**

苗 Aug 2018 – May 2022 (Concurrent) CPA: 4.0

Advised by: Prof. George Konidaris

B.Sc. in Computer Science

Brown University

Aug 2018 – May 2022 (Concurrent) CPA: 3.9

Advised by: Prof. Michael Littman

Courses

ML with Limited Labeled Data Robotics				
NLP with ML Graduate Graphics				
Reintegrating Al Prescriptive Analytics				
ML Theory Seminar	Intro to RL (IS)			
Distributed Systems	Computer Vision			
Accelerated Intro CS	Systems Networks			
Multivariable Calc.	Convex Optimization			
Probability & Stats	Microeconomics			
Blockchains Algorithms Linear Algebra				

PROJECTS

IP/TCP

Implements the IP/TCP system on an abstracted virtual link layer in Rust, with split horizon and poison reverse.

neevparikh/ip-tcp

Volumetric Photon Mapping

Implements volumetric photon mapping by extending an open-source, Rust-based, path tracer, based on Bitterli et. al. (presentation).

O neevparikh/rpt

Hierarchical Doom High-throughput, distributed RL project to implement async. PPO-OC (Proximal Policy Optimized -Option Critic) on the VizDoom environment

Parish (hierarchical-doom)

SKILLS

Pytorch Python Machine Learning					
Rust C++ Slurm AWS Azure					
Numpy Golang C Tensorflow				orflow	
Google Cloud Docker		ker	Git	Haskell	

苗 Jun 2020 – May 2022

📍 Providence, RI

📋 Jun 2019 – Aug 2019

*equal contribution

🞈 Bangalore, India